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## LETTER TO THE EDITOR

# The $\boldsymbol{q}$-deformation of symmetric functions and the symmetric group 

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#### Abstract

The $\boldsymbol{q}$-deformation of symmetric functions is introduced leading to $\boldsymbol{q}$-analogues of many well known relationships in the theory of symmetric functions. $q$-deformed scalar products are developed and used to define $q$-dependent symmetric functions. The symmetric functions commonly associated with the names Hall-Littlewood, Schur and Jack are all special cases of the $q$-deformation of Macdonald's new symmetric functions $P_{\mathrm{A}}(s, t)$. A $q$-analogue of the spin and ordinary characters of $S_{n}$ is given and illustrated by the explicit calculation of examples of $q$-deformed characters. The methods used are closely parallel to those of quantum groups.


Symmetric functions find many applications in physics. The Schur functions (or $S$-functions) arise naturally in the character theory of the symmetric group while the Hall-Littlewood functions find application in the theory of solitons (Nimmo 1990). Macdonald has given a definitive account of both of these types of symmetric functions (Macdonald 1979) as well as their various specializations such as Schur's $Q$-functions that arise in the projective representations of the symmetric group. Throughout we shall follow the notation defined in Macdonald's book (Macdonald 1979).

The characters of the Hecke algebra $H_{n}(q)$ of type $A_{n-1}$ may be calculated by generalizing the power sum symmetric functions as (King and Wybourne 1990)

$$
\begin{equation*}
p_{r}(q ; x)=\sum_{a, b=0, a+b+1=r}^{r-1}(-1)^{b} q^{a} s_{\left(a+1,1^{b}\right)}(x) \tag{1}
\end{equation*}
$$

and for $\rho=\left(\rho_{1}, \rho_{2}, \ldots\right)$ letting

$$
\begin{equation*}
p_{\rho}(q ; x)=p_{\rho_{1}}(q ; x) p_{\rho_{2}}(q ; x) \ldots \tag{2}
\end{equation*}
$$

This could be thought of as a particular type of $q$-deformation of the power sum symmetric function. When $q \rightarrow 1$ (1) becomes the standard relationship between power sum symmetric functions $p_{r}(x)$ and Schur functions $s_{\lambda}(x)$. Indeed if we introduce a $q$-number $[n]_{q}$ such that

$$
\begin{equation*}
[n]_{q}=1+q+q^{2}+\ldots+q^{n} \tag{3}
\end{equation*}
$$

§ On leave from: University of Canterbury, Christchurch, New Zealand.
with $[0]_{q}=1$, we may obtain a $q$-analogue of the usual relationship between the power sum symmetric functions $p_{n}(x)$ and, for example, the complete symmetric functions $h_{n}(x)$ by writing

$$
[n-1]_{q}!h_{n}=\left|\begin{array}{ccccc}
p_{1} & -[0] & & & \ddots  \tag{4}\\
p_{2} & p_{1} & -[1] & & \\
p_{3} & p_{2} & p_{1} & -[2] & \\
\vdots & \vdots & & \ddots & \\
p_{n} & p_{n-1} & \cdots & & p_{1}
\end{array}\right|
$$

where the power sum symmetric functions $p_{r}=\cdot p_{r}(q ; x)$. We have, for example

$$
\begin{equation*}
h_{3}(x)=\frac{p_{1}^{3}+(q+2) p_{21}+(q+1) p_{3}}{(1+q)\left(1+q+q^{2}\right)} \tag{5}
\end{equation*}
$$

For $q=1$ we obtain the usual result

$$
\begin{equation*}
h_{3}=\frac{p_{1}{ }^{3}+3 p_{21}+2 p_{3}}{6} \tag{6}
\end{equation*}
$$

The coefficients in (6) are just the numbers

$$
\begin{equation*}
c(\lambda)=z_{\lambda}^{-1} \tag{7}
\end{equation*}
$$

where as usual (Macdonald 1979, p 17)

$$
\begin{equation*}
z_{\lambda}=\prod_{i} i^{m_{i}} m_{i}! \tag{8}
\end{equation*}
$$

that is

$$
\begin{equation*}
h_{n}(x)=\sum_{|\lambda|=n} z_{\lambda}^{-1} p_{\lambda}(x) \tag{9}
\end{equation*}
$$

The $q$-analogue of (9) is

$$
\begin{equation*}
h_{n}(x)=\sum_{|\lambda|=n}\left(z_{\lambda}^{q}\right)^{-1} p_{\lambda}(q ; x) \tag{10}
\end{equation*}
$$

where

$$
\begin{equation*}
z_{\lambda}^{q}=\prod_{i}[i-1]_{q}^{m_{i}}\left[m_{i}-1\right]_{q}! \tag{11}
\end{equation*}
$$

The above results suggest that it could be useful to explore other types of $q$ deformations of symmetric functions not unlike those considered under the term of quantum groups (cf Drinfeld 1988). It is possible to consistently define various types of $q$-deformations of symmetric functions such as in terms of the $q$-numbers

$$
\begin{equation*}
[n]_{q}=\frac{q^{n}-q^{-n}}{q-q^{-1}} \tag{12}
\end{equation*}
$$

Macdonald has introduced a more general symmetric function $P_{\lambda}(s, t)$ (Macdonald 1988) indexed by partitions $\lambda$ and involving two indeterminates $s$ and $t$. It is useful to consider their $q$-deformation.

Let $x=\left(x_{1}, x_{2}, \ldots\right)$ and $y=\left(y_{1}, y_{2}, \ldots\right)$ be two sequences of indeterminates over $\mathscr{2}(t)$ where $t$ is another indeterminate and define (Macdonald 1979)

$$
\begin{equation*}
P(x, y ; t)=\prod_{i, j} \frac{\left(1-t x_{i} y_{j}\right)}{\left(1-x_{i} y_{j}\right)} . \tag{13}
\end{equation*}
$$

A scalar product $\langle,\rangle_{(t)}$ over $\mathscr{2}(t)$ may be defined as

$$
\begin{equation*}
\left\langle p_{\lambda}, p_{\mu}\right)_{(t)}=\delta_{\lambda \mu} z_{\lambda}(t) \tag{14}
\end{equation*}
$$

where

$$
\begin{equation*}
z_{\lambda}(t)=z_{\lambda} \prod_{i}\left(1-t^{\lambda_{i}}\right)^{-1} \tag{15}
\end{equation*}
$$

Let $s$ be another independent indeterminate and define a scalar product $\langle,\rangle_{(s, t)}$ over $2(s, t)$ as follows

$$
\begin{equation*}
\left\langle p_{\lambda}, p_{\mu}\right\rangle_{(s, t)}=\delta_{\lambda \mu} z_{\lambda}(s, t) \tag{16}
\end{equation*}
$$

where

$$
\begin{equation*}
z_{\lambda}(s, t)=z_{\lambda} \prod_{i} \frac{\left(1-s^{\lambda_{i}}\right)}{\left(1-t^{\lambda_{i}}\right)} \tag{17}
\end{equation*}
$$

We can define a $q$-deformed scalar product $\langle,\rangle_{(s, t)}^{(q)}$ over $\mathscr{Q}_{q}(s, t)$ as

$$
\begin{equation*}
\left\langle p_{\lambda}, p_{\mu}\right\rangle_{(s, t)}^{(q)}=\delta_{\lambda \mu} z_{\lambda}^{q}(s, t) \tag{18}
\end{equation*}
$$

where

$$
\begin{equation*}
z_{\lambda}^{q}(s, t)=\prod_{i}[i-1]_{q}^{m_{i}}\left[m_{i}-1\right]_{q}!\prod_{j}^{l(\lambda)} \frac{\left(1-s^{\left[\lambda_{j}-1\right]_{q}}\right)}{\left(1-t^{\left[\lambda_{j}-1\right]_{q}}\right)} . \tag{19}
\end{equation*}
$$

We call $P_{\lambda}^{q}(s, t)$ the $q$-deformation of the symmetric function $P_{\lambda}(s, t)$.
A $q$-analogue of (13) can be defined as

$$
\begin{equation*}
\mathscr{P}_{q}=\prod_{i, j}\left\{\frac{\left(t x_{i} y_{j} ; s\right)_{\infty}}{\left(x_{i} y_{j} ; s\right)_{\infty}}\right\}_{q} \tag{20}
\end{equation*}
$$

where

$$
\begin{equation*}
(a ; s)_{\infty}=\prod_{r=0}^{\infty}\left(1-a s^{r}\right) \tag{21}
\end{equation*}
$$

and the notation $\{b\}_{q}$ is used for the $q$-deformed expansion of $b$. We then have

$$
\begin{equation*}
\mathscr{P}_{q}(x, y ; s, t)=\sum_{\lambda} z_{\lambda}^{q}(s, t)^{-1} p_{\lambda}(x) p_{\lambda}(y) . \tag{22}
\end{equation*}
$$

The above result follows upon computing $\exp \left(\log \mathscr{P}_{q}\right)$ and leads to a general definition of $q$-deformed symmetric functions in which the usual symmetric functions, such as Hall-Littlewood, Jack, Schur and $Q$-functions, become associated with particular values ( $q, s, t$ ). Setting $q=1$ yields the usual symmetric functions but values of $q$ not a root of unity yield $q$-deformed symmetric functions. For example, $P_{\lambda}^{q}(0, t)$ or simply $P_{\lambda}^{q}(t)$ is the $q$-deformation of the Hall-Littlewood symmetric function. The scalar product $\langle,\rangle_{(i)}^{(q)}$ over $\mathscr{2}(t)$ for this case follows immediately from specialization of (16) and (17).

Let us introduce another symmetric function $Q_{\lambda}^{q}(t)$ related to $P_{\lambda}^{q}(t)$ by a scalar $b_{\lambda}^{q}(t)$ as follows

$$
\begin{equation*}
Q_{\lambda}^{q}(t)=b_{\lambda}^{q}(t) P_{\lambda}^{q}(t) \tag{23}
\end{equation*}
$$

where

$$
\begin{equation*}
b_{\lambda}^{q}(t)=\prod_{i \geqslant 1} \phi_{m_{i}(\lambda)}(t) \quad \phi_{n}^{q}(t)=\prod_{j \neq 1}^{n}\left(1-t^{[j-1]_{q}}\right) . \tag{24}
\end{equation*}
$$

Then

$$
\begin{equation*}
\left\langle P_{\lambda}^{q}(t), Q_{\mu}^{q}(t)\right\rangle_{(t)}^{(q)}=\delta_{\lambda \mu} \tag{25}
\end{equation*}
$$

i.e. $P_{\lambda}^{q}(t), Q_{\lambda}^{q}(t)$ are dual bases of $\Lambda_{2}$ for the scalar product $\langle,\rangle_{(t)}^{(q)}$. It is easy to see that

$$
\begin{align*}
Q_{\lambda}^{q}(t) & =\prod_{i<j}\left\{\frac{1-\delta_{i j}}{1-t \delta_{i j}}\right\}_{q} q_{\lambda}^{q}(t) \\
& =\prod_{i<j}\left(1+(t-1) \delta_{i j}+\left(t^{1+q}+t\right) \delta_{i j}^{2}+\ldots\right) q_{\lambda}^{q}(t) \tag{26}
\end{align*}
$$

where $q_{\lambda}^{q}(t)$ is the projection of $Q_{\lambda}^{q}(t), \delta_{i j}$ is Young's raising operator whose action is defined as $\delta_{i j} q\left(\lambda_{1}, \ldots, \lambda_{i}, \ldots, \lambda_{j}, \ldots\right)=q\left(\lambda_{1}, \ldots, \lambda_{i}+1, \ldots, \lambda_{j}-1, \ldots\right)$.

We are now in a position to give a $q$-analogue of the characters of $S_{n}$. The characters $\chi_{\mu}^{\lambda}$ are elements of a transition matrix that relates Schur functions to power sum symmetric functions via

$$
\begin{equation*}
s_{\lambda}=\sum_{\mu} z_{\mu}^{-1} \chi_{\mu}^{\lambda} p_{\mu} \tag{27}
\end{equation*}
$$

and in the case of the spin characters $\zeta_{\nu}^{\lambda}$ the $Q$-functions are related to the power sum symmetric functions via

$$
\begin{equation*}
Q_{\lambda}=2^{[(/(\lambda)+1(\nu)+1) / 2]} \sum_{\nu} z_{\nu}^{-1} \chi_{\nu}^{\lambda} p_{\nu} . \tag{28}
\end{equation*}
$$

For $s=t, P_{\lambda}^{q}(s, t)$ reduces to the $q$-deformed Schur function $s_{\lambda}^{q}$ and for $s=0$ and $t=-1, P_{\lambda}^{q}(s, t)$ reduces to the $q$-deformed $Q$-function $Q_{\lambda}^{q}$. Thus we are led to the $q$-analogue of (27) and (28) as

$$
\begin{align*}
& s_{\lambda}^{q}=\sum_{\mu}\left(z_{\mu}^{q}\right)^{-1} \chi_{\mu}^{\lambda}(q) p_{\mu}^{q}  \tag{29}\\
& Q_{\Lambda}^{q}=2^{[(f(\lambda)+l(\nu)+1) / 2]} \sum_{\nu}\left(z_{\nu}^{q}\right)^{-1} \zeta_{\nu}^{\lambda}(q) p_{\nu}^{q} . \tag{30}
\end{align*}
$$

The characters $\chi_{\lambda}^{\mu}(q)$ may be calculated using the following algorithm.

1. Expand the $S$-function $s_{\lambda}^{q}$ in terms of complete symmetric functions $h_{\lambda}^{q}$ using the following

$$
\begin{equation*}
s_{\lambda}^{q}=\prod_{i<j}\left(1-\delta_{i j}\right) h_{\lambda}^{q} \tag{31}
\end{equation*}
$$

where $h_{\lambda}^{q} \equiv h_{\lambda_{1}}^{q} h_{i_{2}}^{q} h_{i_{3}}^{q} \ldots$
2. Expand $h_{n}^{q}$ in terms of power sum symmetric functions $p_{\mu}^{q}$ as follows

$$
\begin{equation*}
h_{\eta}^{q}=\sum_{\mu}\left(z_{\mu}^{q}\right)^{-1} p_{\mu}^{q} . \tag{32}
\end{equation*}
$$

Table 1. $q$-dependent characters of $S_{4}$.

|  | $1^{4}$ | $21^{2}$ | 22 | 31 | 4 |
| :--- | :--- | :--- | ---: | ---: | ---: |
| 4 | 1 | 1 | 1 | 1 | 1 |
| 31 | $q+q^{2}+q^{3}$ | $q$ | -1 | 0 | -1 |
| 22 | $q^{2}+q^{4}$ | $1-q$ | $1+q$ | -1 | 0 |
| $21^{2}$ | $q^{3}+q^{4}+q^{5}$ | -1 | $-q$ | 0 | 1 |
| $1^{4}$ | $q^{6}$ | $-q$ | $q$ | 1 | -1 |

Table 2. $q$-Kostka-Foulkes polynomials $K_{\lambda \mu \mu}^{q}(t)$ for $n=4$.

|  | 4 | 31 | 22 | $21^{2}$ | $1_{-}^{4}$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 4 | 1 | $t^{[0]}$ | $t^{[t]}$ | $t^{[2]}$ | $t^{[5]}$ |
| 31 |  | 1 | $t^{[0]}$ | $t^{[0]}+t^{[1]}$ | $t^{[2]}+t^{[3]}+t^{[4]}$ |
| 22 |  |  | 1 | $t^{[0]}$ | $t^{[1]}+t^{[3]}$ |
| $21^{2}$ |  |  |  | 1 | $t^{[0]}+t^{[1]}+t^{[2]}$ |
| $1^{4}$ |  |  |  |  | 1 |

3. $\chi_{\lambda}^{\mu}(q)$ is now found by comparison of the coefficient of $p_{\mu}^{q}$ on both sides of (29).

The $q$-dependent characters for $S_{4}$ following from (29) are given in table 1.
It is easy to see that for $q=1$ we get the usual characters of $S_{4}$.
As a consequence of the above discussion, we are able to give a $q$-analogue of Kostka-Foulkes polynomials $K_{\lambda \mu}(t)$ (cf Macdonald 1979, p 124) which appear in the following expansions

$$
\begin{align*}
& s_{\lambda}^{q}(x)=\sum_{\mu} K_{\lambda \mu}^{q}(t) P_{\mu}^{q}(x ; t)  \tag{33}\\
& Q_{\lambda}^{q}(x ; t)=\sum_{\mu} K_{\lambda \mu}^{q}(t) S_{\mu}^{q}(x ; t) . \tag{34}
\end{align*}
$$

As an example the $q$-Kostka-Foulkes polynomials $K_{\lambda \mu}^{q}(t)$ for $n=4$ are given in table 2.

In the preceding remarks we have noted that it is possible, and we consider fruitful, to study the $q$-deformation of symmetric functions in a rather similar manner to that used in quantum groups. We expect the study of the $q$-deformation of symmetric functions to provide the basis for a more unified treatment of the theory of symmetric functions and we hope eventually to lead to physical applications.
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